

AMENDMENTS TO THE SPECIFICATION

In the Specification

Please substitute the following amended paragraph(s) and/or section(s) (deleted matter is shown by strikethrough and added matter is shown by underlining):

Page 11, line 21:

The capsule profile 2, on the inside of which the rule 1 (not shown in figures 4 to 7) is located, is aligned exactly in parallel with the machine run-off, i.e., the longitudinal movement of the machine head ~~[[1]]~~ 21. For this purpose, use is made of a mounting gauge 20 which aligns the capsule profile 2 at a predetermined distance D from the machine head 21. By moving the machine head 21 along the machine run-off direction and simultaneously applying the mounting gauge 20, an adjustment of the capsule profile 2 in parallel with the moving direction of the machine head 21 is achieved. Figure 5 shows this operation, wherein the machine head 21 effects alignment of the capsule profile 2 by means of the mounting gauge 20.

Page 11 line 29:

The adjusted capsule profile 2 is mounted on the machine bench. Said mounting can be effected in ~~manifold~~ many ways. The embodiment described herein uses a two-step method, wherein, first of all, a coarse alignment of the capsule profile 2 relative to the machine run-off is effected. The machine head 21 is moved to the corresponding (final) positions, and the capsule profile is aligned with the mounting gauge 20 at two points, which are as far apart as possible. After this coarse alignment, a first fixation of the capsule profile 2 may be effected, for example, by loosely tightening a screw connection.

Page 12, line 15:

If the capsule profile 2 is mounted on the machine bench in exact parallel alignment with the run-off of the machine head 21 (Figure 6), the machine head 21 is moved to the sensing head ~~[[16]]~~ 13. In doing so, a predetermined gap 45 is formed between the mounting plate 22, which contacts the mounting surface 15 of the sensing head 13, and the machine head 21. The mounting plate 22, which was hitherto secured on the sensing head 13, is now released therefrom and screwed onto the machine part 21. The gap 45, which previously existed between the mounting plate 22 and the machine head 21, is thus shifted to between the mounting plate 22 and the sensing head 13. Said gap serves as an adhesive gap 30, which is then filled with adhesive in order to securely mount the mounting head 13 on the mounting plate 22, which is screwed onto the mounting element 21 (see Figure 7). In doing so, the adhesive can cure free from stresses.

Page 14, line 33:

This operation is shown in Figure 13, which shows the mounting plate 22 mounted on the machine part 21 (not shown) via screws ~~[[42]]~~ 43. A nozzle 44 is fitted into the funnel tube 35, said nozzle 44 serving to introduce adhesive into the volume 33 for adhesive, via the oblique inlet surface 42, so as to adhere the sensing head 13 to the mounting plate 22. The U-shaped circumferential edge 32 of the mounting plate 22, which protrudes into the recess 40 on the mounting surface 15 of the sensing head 13, ensures that the adhesive introduced does not flow out of the bottom or the sides of the volume 33 for adhesive.

Page 15, line 8:

Figure 14 shows the condition after jointing, just before completion of the final assembly, now representing the capsule profile 2 including the rule 1. As can be seen, the sensing head 13 protrudes deeply into the capsule profile 2. The sensing head ~~[[14]]~~ 13 embraces the rule 1 on three sides, without contacting it or being supported thereon, upon completion of the final assembly, i.e. upon removal of the fitting pieces. In Figure 14, the upper fitting cylinder 18 has already been withdrawn from the upper holding groove 11 and from the upper grooves 16 (hidden in this view) of the sensing head 13, whereas the lower fitting cylinder 19 has not yet been withdrawn. Upon removal of the lower fitting cylinder 19 from the lower holding groove 12 and from the lower groove 17, the sensing head 14 mounted on the machine head 21 is freely movable along the rule 1, the path of its movement being defined by the movement of the machine head 21. In case the sensing head 13 is to be released from the machine head 21, the screws 43 may be screwed out, thus enabling removal of the sensing head 13, together with the mounting plate 22, from the machine head 21.